# Relations between entropies produced in nondeterministic thermodynamic processes 

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#### Abstract

Landauer's erasure principle is generalized to nondeterministic processes on systems having an arbitrary number of nonsymmetrical logical states. The condition that the process is applied in the same way, irrespective of the initial logical state, imposes some restrictions on the individual heat exchanges associated with each possible transition. The complete set of such restrictions are derived by a statistical analysis of the phase-space flow induced by the process. Landauer's erasure principle can be derived from and is a special case of these.


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## I. INTRODUCTION

Landauer's erasure principle (LEP) is a fundamental result in the thermodynamics of computation. It gives a relation between the amount of the information stored by a memory device and the average entropy increase in the environment when a process erases that information. The principle holds for processes that satisfy two essential features:
(A) The process is carried out in the same way independent of the initial logical state (i.e., the information stored) or the microstate of the device and
(B) it restores the device to a known standard state at the end.

The first feature is necessary for a complete erasure of information. Although it is conceivable that the process can read the information and take different actions depending on it, this can be done only by recording the information somewhere else. In that case, the process must also erase the recorded information. Even when this is the case, the statement (A) remains valid when the recording instrument is considered as part of the device.

Landauer [1] has shown that under both of these conditions, heats must be dumped to the environment in such a way that the average increase in the entropy is at least $k_{B} \ln 2$ per bit of the information erased, where $k_{B}$ is Boltzmann's constant. The original derivation of the principle by Landauer also assumes that the logical states of the device are symmetric, i.e., they have equal values for the thermodynamical quantities. However, such a restriction is not necessary when the total entropy change of both the device and the environment is considered. For example, for devices having nonsymmetrical logical states, it is seen that the main conclusion of LEP continues to be valid when a complete writeerase cycle is considered [2].

The principle is of prime importance in Bennett's resolution of Maxwell's demon paradox [3]. In its quest to reduce entropy, the demon periodically makes measurements, records the results into its memory, and takes some actions depending on these results. As the memory has a finite capacity, it must be cleared at some stage and reset to some standard state in order to repeat the same cycle of events. It is this erasure process and the associated entropy increase that exactly offsets the reduction in entropy the demon has achieved and thus saves the second law. Independently from

Landauer and Bennett, same conclusions have been obtained by Penrose [4] in his textbook on statistical mechanics. A review of Landauer's principle and Maxwell's demon, as well as reprints of some key articles can be found in Ref. [5].

Since Landauer's original derivation of LEP relies on the second law where the definition of entropy is extended to an ensemble of memory devices, several objections have been raised on its validity. This prompted the appearance of alternative proofs of the principle that does not rely on the second law, by using the Fokker-Planck equation [6], by using the microstate distribution functions [7], and by analyzing the phase-space flow the erasing process induces [8].

In all of these, the feature (A) of the process is of central importance. Since the device and the environment are subjected to the same treatment independent of the initial logical state, feature (A) is equivalent to the statement that the time dependence of the microstates during the process is governed by a single, logical-state-independent Hamiltonian. As a result, the microstates before and after the process are related by a single map. That map is a canonical transformation for classical systems, which preserves the phase-space volumes by Liouville's theorem, and is an isometry for quantum systems, which preserves the dimensions of the subspaces it is acting to. LEP follows from the constancy of the phase-space measures: as the process necessarily reduces the phase space of the device by requirement (B), it must expand that of the environment which leads to the Landauer bound.

The purpose of this paper is to investigate the full implications of the feature (A) in the most general setting, without any additional assumptions. It contains the derivation of a complete set of relations that captures all restrictions that can be placed on the heats dumped to the environment in such processes. When deriving these relations, no further assumptions are made on the process and the logical states of the system. The logical states might be nonsymmetrical and, in addition, the initial and final sets of these states might be different both in number and in character. Also, the process applied can be nondeterministic, i.e., for the same initial logical state, it might lead to a set of different final states with known transition probabilities. The precise statement that will be proved is the following:

Theorem 1. Suppose that an arbitrary process having feature (A) is applied on a system that has $n$ initial logical states and brings it to a final configuration with $m$ logical states. If $P(\beta \mid \alpha)$ denotes the conditional probability that the initial logical state $\alpha$ ends up in the final logical state $\beta$, and $k_{B} s_{\beta \alpha}$
denotes the total entropy increase in the system and the environment when an $\alpha$ to $\beta$ transition occurs, then the following inequalities are satisfied:

$$
\begin{equation*}
\sum_{\alpha=1}^{n} P(\beta \mid \alpha) e^{-s_{\beta \alpha}} \leq 1 \quad(\beta=1,2, \ldots, m) \tag{1}
\end{equation*}
$$

i.e., $m$ inequalities, one for each possible final state $\beta$.

No additional assumptions other than feature (A) will be made in proving this theorem. If the process obtains some information about the system and stores it into some recording instrument or, in general, an interaction occurs with an instrument, then the instrument should be considered as part of the system. Apart from this, if the initial logical state of the system is recorded elsewhere before the process begins, the conclusions of the theorem will not change as long as the process does not use this information.

These relations imply LEP as a special case [when feature (B) is also imposed], but they go far beyond LEP in implications because they cannot be derived starting from this principle. It will also be shown that these relations are complete, i.e., one cannot find any further restrictions between the transition probabilities and individual entropy increases. Consequently, any process with parameters satisfying Eq. (1) can be constructed in principle. Therefore, these inequalities provide a complete description of the thermodynamics of classical information processing by taking nondeterministic logical operations into account. Like LEP, these relations are mainly of theoretical interest, but they may find application in the investigation of heat exchange requirements of probabilistic Turing machines. The heat exchanges for nondeterministic processes have previously been analyzed by Penrose [4]. They are also investigated in detail by Maroney $[9,10]$ for the purpose of generalizing LEP. However, as it is shown in this paper, their entropic restrictions on heat exchanges are weaker than theorem 1.

The organization of the paper is as follows. In Sec. II: first, the notation used for describing the systems and the processes is defined. Then, concentrating on the constant temperature case, the proof of theorem 1 is given for both classical and quantum systems. Finally, the completeness of these relations is proved by constructing an arbitrary process on a simple system. In Sec. III, the connection between relations (1) and previously known relations such as LEP is discussed. Section IV contains a brief conclusion. Finally, the Appendix contains the proof of the theorem for the case of various baths at different temperatures.

## II. RELATIONS BETWEEN HEATS DUMPED

## A. Definitions and notation

Consider a system $S$ which can have two possibly identical configurations which will be called initial and final configurations. In the initial configuration, the system has $n$ distinct logical states described by a Hamiltonian $H_{i S}$ and is in equilibrium with a heat bath $B_{i}$ at temperature $T_{i}$. In the final configuration, the system has $m$ distinct logical states described by Hamiltonian $H_{f S}$ and is in equilibrium with a bath $B_{f}$ at temperature $T_{f}$. The two baths might be identical. The
system can be microscopic, but all of the baths must be macroscopic.

A process brings the system from the initial configuration to the final configuration, while in the meantime it brings the system into contact with various heat baths $B_{j}$ at different temperatures $T_{j}$. Any process satisfying the feature (A) can be described as a time-dependent Hamiltonian

$$
\begin{equation*}
\mathcal{H}(t)=H_{S}(\mathbf{s} ; t)+H_{\mathrm{int}}\left(\mathbf{s} ; \mathbf{b}_{i}, \mathbf{b}_{2}, \ldots, \mathbf{b}_{f} ; t\right)+\sum_{j} H_{B_{j}}\left(\mathbf{b}_{j}\right) \tag{2}
\end{equation*}
$$

where $\mathbf{s}$ and $\mathbf{b}_{j}$ denote the phase-space coordinates of the system $S$ and the bath $B_{j}$ respectively, $H_{B_{j}}$ is the Hamiltonian of bath $B_{j}$ and $H_{\text {int }}$ describes the detailed coupling of the system to the baths. If the process starts at time $t_{i}$ and ends at $t_{f}$, the total Hamiltonian reduces to the corresponding expressions for each configuration. In other words, for $t \leq t_{i}$,

$$
\begin{equation*}
\mathcal{H}(t)=H_{i S}(\mathbf{s})+H_{i, \mathrm{int}}\left(\mathbf{s} ; \mathbf{b}_{i}\right)+\sum_{j} H_{B_{j}}\left(\mathbf{b}_{j}\right) \tag{3}
\end{equation*}
$$

and for $t \geq t_{f}$,

$$
\begin{equation*}
\mathcal{H}(t)=H_{f S}(\mathbf{s})+H_{f, \text { int }}\left(\mathbf{s} ; \mathbf{b}_{f}\right)+\sum_{j} H_{B_{j}}\left(\mathbf{b}_{j}\right) . \tag{4}
\end{equation*}
$$

In both of these configurations, it will be assumed that the coupling terms $H_{c, \text { int }}\left(\mathbf{s}, \mathbf{b}_{c}\right)(c=i, f)$ are negligibly small. If $H_{f, \text { int }}$ is identically zero, then sufficiently long times should pass during the process for an effective equilibration.

The phase space of the system is divided into disjoint regions corresponding to each logical state in such a way that any microstate $\mathbf{s}$ belongs to one and only one logical state. This division can be described with indicator functions $\theta_{c \alpha}$ which are defined as $\theta_{c \alpha}(\mathbf{s})=1$ when $\mathbf{s}$ belongs to logical state $\alpha$ in configuration $c$ and $\theta_{c \alpha}(\mathbf{s})=0$ otherwise. As a result, $\Sigma_{\alpha} \theta_{c \alpha}(\mathbf{s})=1$ must be satisfied for all $\mathbf{s}$.

Miscellaneous thermodynamical quantities for each logical state must be defined in the canonical ensemble by using only those microstates that belong to the given logical state. Thus, using the indicator functions, the partition function and the internal energy are

$$
\begin{gather*}
Z_{c \alpha}=\int \theta_{c \alpha}(\mathbf{s}) e^{-H_{c S}(\mathbf{s}) / k_{B} T_{c}} d \mathbf{s}  \tag{5}\\
U_{c \alpha}=\frac{1}{Z_{c \alpha}} \int H_{c S}(\mathbf{s}) \theta_{c \alpha}(\mathbf{s}) e^{-H_{c S}(\mathbf{s}) / k_{B} T_{c}} d \mathbf{s} \tag{6}
\end{gather*}
$$

respectively and the free energy, $F_{c \alpha}=-k_{B} T_{c} \ln Z_{c \alpha}$, and entropy, $S_{c \alpha}=\left(U_{c \alpha}-F_{c \alpha}\right) / T_{c}$, are defined accordingly.

The logical states must be sufficiently stable in such a way that they can be used for information storage purposes, i.e., once the system is in one of the logical states, either it does not make a transition into another logical state, or the transition time scales are long compared to the process and equilibration time scales. In the former case, impenetrable barriers separate the microstates of different logical states and the above quantities correspond to the exact canonical thermodynamical functions. In the latter case, high thermal or diffusion barriers with long transition times separate the logical states and there is some arbitrariness in the choice of
the indicator functions. Once this choice is made, however, the thermodynamical functions must be defined as above.

In the proof, the canonical map between the microstates of the composite system of $S$ and the baths for two given times $t_{1}$ and $t_{2}$ will be investigated ( $t_{1} \leq t_{i}<t_{f} \leq t_{2}$ ). It will be supposed that the system is prepared such that, at time $t_{1}$ it is in logical state $\alpha$ of the initial configuration and in equilibrium with the bath $B_{i}$. The initial distribution of the microstates of the composite system depends on the preparation, but it must be consistent with the equilibrium assumption. Consider the microstate of the composite system at time $t_{2}$ after the process is applied. Let $P(\beta \mid \alpha)$ be the probability that the final microstate belongs to logical state $\beta$ of final configuration. Let $W(\beta \leftarrow \alpha)$ denote the average work done given that an $\alpha$ to $\beta$ transition occurs. This is the conditional average of the total energy change of the system and the baths over all microstates that take part in $\alpha$ to $\beta$ transition. Similarly let $Q_{j}(\beta \leftarrow \alpha)$ denote the average amount of heat transferred to the bath $B_{j}$ given that $\alpha$ to $\beta$ transition occurs. As these quantities must be computed in equilibrium, $t_{2}-t_{f}$ must be sufficiently large for getting thermal equilibrium at time $t_{2}$. Moreover, $t_{i}-t_{1}$ must be sufficiently large for thermal equilibration. Provided that both of these conditions are satisfied, the conditional averages of the initial and final energies of the system over microstates that take part in $\alpha$ to $\beta$ transition are $U_{i \alpha}$ and $U_{f \beta}$. Therefore, the quantities above are related by the first law,

$$
\begin{equation*}
U_{f \beta}-U_{i \alpha}=W(\beta \leftarrow \alpha)-\sum_{j} Q_{j}(\beta \leftarrow \alpha) \tag{7}
\end{equation*}
$$

The total entropy change per $k_{B}$ in $\alpha$ to $\beta$ transition will be denoted by $s_{\beta \alpha}$ and is given by

$$
\begin{equation*}
k_{B} s_{\beta \alpha}=S_{f \beta}-S_{i \alpha}+\sum_{j} \frac{Q_{j}(\beta \leftarrow \alpha)}{T_{j}} . \tag{8}
\end{equation*}
$$

In order to interpret these quantities as the total entropy change, the baths must be sufficiently large so that the heats dumped $Q_{j}(\beta \leftarrow \alpha)$ cannot change their temperature.

Before going further, it is worth to consider an important special case, the constant-temperature case, where the system is in contact with a single bath at temperature $T$ (where $B_{i}$ $=B_{f}$ and $T_{i}=T_{f}=T$ ). In that case, the quantities $s_{\beta \alpha}$ can be given a simple meaning in terms of the heat emitted to the bath or the work done on the system. These quantities can be expressed in terms of $s_{\beta \alpha}$ as

$$
\begin{gather*}
W(\beta \leftarrow \alpha)=F_{f \beta}-F_{i \alpha}+k_{B} T s_{\beta \alpha},  \tag{9}\\
Q(\beta \leftarrow \alpha)=-T\left(S_{f \beta}-S_{i \alpha}\right)+k_{B} T s_{\beta \alpha} . \tag{10}
\end{gather*}
$$

Note that, when some other thermodynamically reversible deterministic process brings the system from $\alpha$ to $\beta$, $-T\left(S_{f \beta}-S_{i \alpha}\right)$ is the exact amount of heat that must be dumped to the bath. For the current nondeterministic process however, the heat dumped exceeds that reversible contribution by $k_{B} T s_{\beta \alpha}$. For this particular reason, for the constant temperature case, it is tempting to call $s_{\beta \alpha}$ as the dimensionless excess heat (in units of $k_{B} T$ ) associated with this particular transition. For the same reason, it can also be called as the
dimensionless excess work. Despite what the name may imply, the excess heats can be negative for nondeterministic transitions.

The excess heats are convenient quantities to be concentrated on, because in a cyclic change where a set of processes bring the system back to the initial configuration and state, all reversible contributions in Eq. (10) add up to zero. The sum of excess heats then gives the total heat dumped to the bath. This is the case in the context of Maxwell's demon, for example. In this way, the inconvenience brought by the asymmetry of the states is eliminated.

## B. Proof of theorem 1 for the classical case

This subsection contains the proof of theorem 1 for a classical system. To make the derivation as clear as possible, it is assumed that the system interacts with a single bath $B$ at temperature $T$. The proof of the general case, which involves various baths at different temperatures, is not different from the proof given below, but the notation is more involved. For this reason, the sketch of the general proof is given in the Appendix.

The proof relies on the following approximations which are justified by the largeness of the bath. (1) At the initial preparation stage, the total energy $E$ of the composite system $S+B$ has an arbitrary distribution in a certain range of energies, say between $E_{\min }$ and $E_{\max }$. For any $E$ in this interval, the associated microcanonical temperature of composite system is approximately $T$. (2) The width of the range, $E_{\max }$ $-E_{\min }$, is much larger than the typical energies for the system. (3) Given that the initial energy of $S+B$ at time $t_{1}$ is $E$, the process parameters $P(\beta \mid \alpha), W(\beta \leftarrow \alpha)$ and $Q(\beta \leftarrow \alpha)$ of the process is approximately independent of $E$ for $E_{\min } \leq E$ $\leq E_{\max }$. The errors made from these approximations will get smaller as the size of the bath increases. The last assumption enables us to investigate the relationship between these quantities within the microcanonical ensemble formalism. In other words, it is supposed that the initial states of the composite system have total energy $E$ within the aforementioned range, and the microstates are distributed with equal a priori probabilities. The basic method is to express the transition probabilities in terms of certain disjoint phase-space volumes. A particular addition of these volumes leads directly to the inequalities of theorem 1.

The process induces a canonical transformation $\phi$ on the total phase space of $S+B$ from $t_{1}$ to $t_{2}$. Let $\phi$ map the initial points $(\mathbf{s}, \mathbf{b})$ to the final points $\left(\mathbf{s}^{\prime}, \mathbf{b}^{\prime}\right)=\phi(\mathbf{s}, \mathbf{b})$. Since $\phi$ is canonical, it preserves volumes by Liouville's theorem, i.e., the phase-space volume elements are equal, $d \mathbf{s} d \mathbf{b}=d \mathbf{s}^{\prime} d \mathbf{b}^{\prime}$.

Let $n_{B}(E) d E$ represent the phase-space volume of the bath consisting of points having energy between $E$ and $E+d E$. The corresponding density is

$$
\begin{equation*}
n_{B}(E)=\int \delta\left[E-H_{B}(\mathbf{b})\right] d \mathbf{b} \tag{11}
\end{equation*}
$$

As a result of the assumptions made above, the relation

$$
\begin{equation*}
n_{B}(E-\Delta E)=n_{B}(E) e^{-\Delta E / k_{B} T} \tag{12}
\end{equation*}
$$

holds with good accuracy for typical energies $\Delta E$ of the system.

Let $N_{c \alpha}(E) d E$ represent the volume of the total phase space of $S+B$ of those microstates having energy between $E$ and $E+d E$ and belonging to state $\alpha$ of system $S$ in configuration $c$. The corresponding density is

$$
\begin{align*}
N_{c \alpha}(E) & =\int d \mathbf{s} d \mathbf{b} \delta\left[E-H_{c S}(\mathbf{s})-H_{B}(\mathbf{b})\right] \theta_{c \alpha}(\mathbf{s}) \\
& =\int d \mathbf{s} n_{B}\left[E-H_{c S}(\mathbf{s})\right] \theta_{c \alpha}(\mathbf{s}) \\
& =n_{B}(E) \int d \mathbf{s} \exp \left[-H_{c S}(\mathbf{s}) / k_{B} T\right] \theta_{c \alpha}(\mathbf{s}) \\
& =n_{B}(E) Z_{c \alpha} . \tag{13}
\end{align*}
$$

In here, the interaction terms representing bath-system coupling are dropped assuming that they are negligible.

Finally, let $M_{\beta \alpha}\left(E^{\prime}, E\right) d E^{\prime} d E$ be the volume of phasespace points of $S+B$ that start at state $\alpha$ with energy between $E$ and $E+d E$ and end up at state $\beta$ with energy between $E^{\prime}$ and $E^{\prime}+d E^{\prime}$. The corresponding density can be expressed as

$$
\begin{align*}
M_{\beta \alpha}\left(E^{\prime}, E\right)= & \int d \mathbf{s} d \mathbf{b} \delta\left[E-H_{i S}(\mathbf{s})-H_{B}(\mathbf{b})\right] \theta_{i \alpha}(\mathbf{s}) \\
& \times \delta\left[E^{\prime}-H_{f S}\left(\mathbf{s}^{\prime}\right)-H_{B}\left(\mathbf{b}^{\prime}\right)\right] \theta_{f \beta}\left(\mathbf{s}^{\prime}\right) \tag{14}
\end{align*}
$$

Note that $M_{\beta \alpha}\left(E^{\prime}, E\right)$ represents the density of points where an $\alpha$ to $\beta$ transition has occurred and the total energy has increased by $E^{\prime}-E$. In that case, $E^{\prime}-E$ is the total work done.

Now, suppose that the total energy of $S+B$ was $E$ and the system was in state $\alpha$ before the process is applied. Then, by equal a priori probabilities assumption, $S+B$ is in one of the microstates consistent with these restrictions with equal probability. In that case, the probability that a transition to state $\beta$ occurs with final energy between $E^{\prime}$ and $E^{\prime}+d E^{\prime}$ can be expressed as

$$
\begin{equation*}
\frac{M_{\beta \alpha}\left(E^{\prime}, E\right) d E^{\prime}}{N_{i \alpha}(E)} \tag{15}
\end{equation*}
$$

Let $P(\beta \mid \alpha ; E)$ be the probability of making an $\alpha$ to $\beta$ transition, irrespective of the work done, and let $\mathcal{P}_{\beta \alpha}(w ; E)$ be the probability distribution function for the work done $w$ in the $\alpha$ to $\beta$ transition. These probabilities can be expressed as

$$
\begin{gather*}
P(\beta \mid \alpha ; E)=\int \frac{M_{\beta \alpha}\left(E^{\prime}, E\right) d E^{\prime}}{N_{i \alpha}(E)},  \tag{16}\\
\mathcal{P}_{\beta \alpha}(w ; E)=\frac{M_{\beta \alpha}(E+w, E)}{P(\beta \mid \alpha ; E) N_{i \alpha}(E)} . \tag{17}
\end{gather*}
$$

As discussed above, both of these probabilities have only a weak dependence on $E$, which can be considered to be a dependence on the temperature $T$. For this reason, we will write $P(\beta \mid \alpha ; E)=P(\beta \mid \alpha)$ and $\mathcal{P}_{\beta \alpha}(w ; E)=\mathcal{P}_{\beta \alpha}(w)$; the dependence on the temperature is assumed, but not shown ex-
plicitly. Combining these with Eq. (13) we get

$$
\begin{equation*}
M_{\beta \alpha}\left(E^{\prime}, E\right)=n_{B}(E) Z_{i \alpha} P(\beta \mid \alpha) \mathcal{P}_{\beta \alpha}\left(E^{\prime}-E\right) \tag{18}
\end{equation*}
$$

This equation relates the phase-space volume densities to the process dependent quantities: the transition probabilities and the distribution function for the work done in individual transitions.

To obtain the inequalities of the theorem, we sum Eq. (14) over the initial logical states and integrate over $E$ which gives

$$
\begin{align*}
\sum_{\alpha} \int d E M_{\beta \alpha}\left(E^{\prime}, E\right)= & \int^{\prime} d \mathbf{s}^{\prime} d \mathbf{b}^{\prime} \\
& \times \delta\left[E^{\prime}-H_{f S}\left(\mathbf{s}^{\prime}\right)-H_{B}\left(\mathbf{b}^{\prime}\right)\right] \theta_{f \beta}\left(\mathbf{s}^{\prime}\right) \tag{19}
\end{align*}
$$

where the equality of the volume elements, $d \mathbf{s} d \mathbf{b}=d \mathbf{s}^{\prime} d \mathbf{b}^{\prime}$, is used and the prime on the integral sign indicates that the integration is over all possible final microstates. This integral is not over the whole of the phase space when the process map $\phi$ is not onto. This may happen when infinite, impenetrable barriers evacuate some part of the phase space. For example, this is the case for the erasure process considered by Landauer where all final logical states other than the standard state are inaccessible. For this reason, the right-hand side of Eq. (19) is smaller than the integral over the whole of phase space,

$$
\begin{equation*}
\sum_{\alpha} \int d E M_{\beta \alpha}\left(E^{\prime}, E\right) \leq N_{f \beta}\left(E^{\prime}\right)=n_{B}\left(E^{\prime}\right) Z_{f \beta} . \tag{20}
\end{equation*}
$$

This is the first place where an inequality is introduced. The equality holds if and only if $\phi$ is onto.

Using Eq. (18) and changing the integration variable to $w=E^{\prime}-E$ gives

$$
\begin{align*}
\sum_{\alpha} & P(\beta \mid \alpha) \int d w \mathcal{P}_{\beta \alpha}(w) e^{-\left(w+F_{i \alpha}-F_{f \beta}\right) / k_{B} T} \\
& =\sum_{\alpha} P(\beta \mid \alpha)\left\langle e^{-w / k_{B} T}\right\rangle_{\beta \alpha} e^{-\left(F_{i \alpha}-F_{f \beta}\right) / k_{B} T} \leq 1 \tag{21}
\end{align*}
$$

where $\langle\cdots\rangle_{\beta \alpha}$ represents the conditional average over microstates that take part in $\alpha$ to $\beta$ transition. Using the strict convexity of the exponential function we get $\exp \left(-\langle w\rangle_{\beta \alpha} / k_{B} T\right) \leq\left\langle\exp \left(-w / k_{B} T\right)\right\rangle_{\beta \alpha}$ where equality holds if and only if work done has no fluctuations. Finally, using $\langle w\rangle_{\beta \alpha}=W(\beta \leftarrow \alpha)$ and relation (9), we get the desired inequality in Eq. (1).

Inequalities are introduced at two points; therefore if a process has equalities for all of these $m$ relations, the process map $\phi$ on the total phase space should be onto and works done should have absolutely no fluctuations. We will define $I_{\beta}$, the inefficiency of the process for the final state $\beta$, as

$$
\begin{equation*}
e^{-I_{\beta}}=\sum_{\alpha} P(\beta \mid \alpha) e^{-s_{\beta \alpha}} \tag{22}
\end{equation*}
$$

Relations (1) then imply that all inefficiencies are nonnegative. Inefficiencies are essentially a combined measure of the irreversibility of the process and the fluctuations in the
energy exchanges. As it will be seen below, by process engineering, some excess heats can be reduced and all inefficiencies can be made to vanish. In the case of an efficient process, where all $I_{\beta}=0$, it is not possible to decrease any of the excess heats without increasing some other excess heat corresponding to a transition with the same final state. By the discussion above, efficient processes have no fluctuation for the excess heats and the process map is onto.

It might be interesting to view the derivation above from the perspective of the time-reversed process. The time reversal of a process is always well defined in the Hamiltonian description; it is simply given by the Hamiltonian $\widetilde{\mathcal{H}}(t)$ $=\mathcal{H}(-t)$ and brings the system from the final configuration to the initial one. Basically, one needs to carry out the same actions in reverse order. Below, the associated quantities for the reverse process will be indicated by tildes. For simplicity, consider the case where $\phi$ is onto. As the reversed process map is $\widetilde{\phi}=\phi^{-1}$, the densities in Eq. (14) are related by $\tilde{M}_{\alpha \beta}\left(E, E^{\prime}\right)=M_{\beta \alpha}\left(E^{\prime}, E\right)$. Invoking Eq. (18), the following relation between the probability distributions can be found:

$$
\begin{equation*}
\widetilde{P}(\alpha \mid \beta) \widetilde{\mathcal{P}}_{\alpha \beta}(-w)=P(\beta \mid \alpha) \mathcal{P}_{\beta \alpha}(w) e^{-w / k_{B} T} \frac{Z_{i \alpha}}{Z_{f \beta}} \tag{23}
\end{equation*}
$$

That relation can be made simpler by expressing it in terms of a microstate dependent variable for the excess heat, $s=\left(w+F_{i \alpha}-F_{f \beta}\right) / k_{B} T$. Note that $\langle s\rangle_{\beta \alpha}=s_{\beta \alpha}$ and $s$ has no fluctuations if and only if $w$ has no fluctuations. This variable can also be expressed as a function of the microstate coordinates as

$$
\begin{align*}
s= & \frac{1}{k_{B} T}\left(\sum_{\gamma} F_{i \gamma} \theta_{i \gamma}(\mathbf{s})-\sum_{\gamma} F_{f \gamma} \theta_{f \gamma}\left(\mathbf{s}^{\prime}\right)+H_{f S}\left(\mathbf{s}^{\prime}\right)+H_{B}\left(\mathbf{b}^{\prime}\right)\right. \\
& \left.-H_{i S}(\mathbf{s})-H_{B}(\mathbf{b})\right), \tag{24}
\end{align*}
$$

for the forward process. Therefore, for the reversed process with initial point at $\left(\mathbf{s}^{\prime}, \mathbf{b}^{\prime}\right)$, the value of the corresponding variable is $-s$. The relationship between the probability distributions of $s$ for forward and reverse processes then becomes

$$
\begin{equation*}
\widetilde{P}(\alpha \mid \beta) \widetilde{\mathcal{P}}_{\alpha \beta}^{\prime}(-s)=P(\beta \mid \alpha) \mathcal{P}_{\beta \alpha}(s) e^{-s} \tag{25}
\end{equation*}
$$

where $\mathcal{P}^{\prime}$ denotes the distribution function for that quantity. Inequalities (1) are obtained by using the fact that the total probability for the reversed process is 1 .

## C. Sketch of the proof for quantum systems

For quantum systems, there is a problem involved in definition (8) of $s_{\beta \alpha}$. To provide a consistent definition of these quantities, it should be assumed that the system starts from a definite initial logical state $\alpha$ and when the process is completed a projective measurement of the final logical state is carried out. Provided that this is done, the average heats dumped to the baths can be computed from the expectation value of the respective Hamiltonians of the baths and therefore $s_{\beta \alpha}$ are well-defined quantities. It is important that such a final measurement stage takes place to eliminate the possi-
bility of having final microstates in a superposition state of various logical states. If this is the case, the inequalities of theorem 1 are valid.

The proof for this case is not different from the classical proof given above. There is only a change in the terms used. Instead of a canonical map, there is now an isometry $V$ that maps the initial microstates into the final ones, which preserve the dimensions of the subspaces $\left(V^{\dagger} V=1\right)$. As above, the map $V$ does not need to be onto, i.e., it does not need to be unitary. In that case, $V V^{\dagger}$ is a projection operator on the accessible final states and therefore $V V^{\dagger} \leq 1$.

The operators $\theta_{c \alpha}$ are now a complete set of orthogonal projections $\left(\sum_{\alpha} \theta_{c \alpha}=1\right)$ which commute with the respective Hamiltonians $H_{c s}$. All of the phase-space densities defined above can now be expressed as

$$
\begin{gather*}
n_{B}(E)=\operatorname{tr} \delta\left(E-H_{B}\right),  \tag{26}\\
N_{c \alpha}(E)=\operatorname{tr}\left[\delta\left(E-H_{c S}-H_{B}\right) \theta_{c \alpha}\right],  \tag{27}\\
M_{\beta \alpha}\left(E^{\prime}, E\right)= \\
\operatorname{tr}\left[V \delta\left(E-H_{i S}-H_{B}\right) \theta_{i \alpha} V^{\dagger}\right.  \tag{28}\\
\left.\times \delta\left(E^{\prime}-H_{f S}-H_{B}\right) \theta_{f \beta}\right] .
\end{gather*}
$$

The identity in Eq. (18) remains the same. The inequality in Eq. (20) follows by using the fact that $V V^{\dagger} \leq 1$ and the same convexity argument leads to the final proof.

## D. Completeness of the relations in theorem 1

The set of inequalities (1) are also complete. In other words, one cannot find any more restrictions between the transition probabilities and entropy increases that cannot be derived from the given inequalities. This completeness statement is captured in the following theorem.

Theorem 2. Let $P(\beta \mid \alpha)$ be some transition probabilities and $s_{\beta \alpha}(\beta=1, \ldots, m, \alpha=1, \ldots, n)$ be some numbers such that none of $s_{\beta \alpha}$ are infinite and the quantities $I_{\beta}$, which are defined as

$$
\begin{equation*}
\sum_{\alpha} P(\beta \mid \alpha) e^{-s_{\beta \alpha}}=e^{-I_{\beta}} \tag{29}
\end{equation*}
$$

are nonnegative. Then, there is a system $S$ having initial and final configurations with, respectively, $n$ and $m$ logical states, and there is a process having feature $(\mathrm{A})$ on that system such that $P(\beta \mid \alpha)$ are the transition probabilities and $s_{\beta \alpha}$ are the total entropy increases for the respective individual transitions.

Proof. The system that will be chosen for this purpose is essentially Szilard's one molecule gas [11]. It is a classical system which is composed of a single molecule inside a box with a total volume $V$ and in contact with a heat bath at temperature $T$ (Fig. 1). The box is divided by impenetrable walls into $n$ regions having volumes $R_{i \alpha} V(\alpha=1,2, \ldots, n)$ for the initial configuration and into $m$ regions having volumes $R_{f \alpha} V(\alpha=1,2, \ldots, m)$ for the final configuration. Here $R_{c \alpha}$ are positive numbers with $\Sigma_{\alpha} R_{c \alpha}=1$. The region that the molecule is located represents the logical state and all of them are separated by impenetrable barriers.

Although it is not essential for the proof of the theorem, it can be supposed that different constant potentials are applied


FIG. 1. The steps of the process on a single molecule system with $n=2$ initial and $m=3$ final logical states. The system is prepared in initial configuration and (1) potentials of each region are lowered to zero, (2) additional walls are inserted, (3) volume of each region is expanded or compressed, (4) some parts of the walls are removed, (5) walls are aligned at constant volume, (6) each region is compressed adiabatically by pistons from left, (7) small holes opened on the pistons to let the molecule expand freely toward the left part, and finally (8) pistons are removed and the potentials of each region are increased.
to each region. If the molecule is an ion, this can be achieved by surrounding each region by a metallic sheet and applying different constant electrostatic potentials to them. Let $u_{c \alpha}$ be the potential energy in region $\alpha$ for configuration $c$. This potential does not affect the motion of the molecule; its sole purpose is to adjust the internal energies of states to different values. The internal energy and entropies of the molecule can be expressed as

$$
\begin{gather*}
U_{c \alpha}=u_{c \alpha}+f(T),  \tag{30}\\
S_{c \alpha}=k_{B} \ln \left(R_{c \alpha} V\right)+g(T), \tag{31}
\end{gather*}
$$

for some functions $f$ and $g$ of temperature. Therefore, by selecting $u_{c \alpha}, R_{c \alpha}$ and the volume $V$ appropriately, it is possible to set the values of internal energy and entropies to anything that we choose. As it will be seen below, these values do not have any effect on the end results; they are completely arbitrary.

Consider the following process applied on this gas. Note that all of the individual steps of this process can be carried out without knowing where the molecule is. Therefore, it is a process that satisfies the condition (A). At each step, only the value of the work done is computed; the heat exchange with the bath can be computed from the first law at the final stage.

Prepare the box in the initial configuration. The molecule can be in any region.
(1) First, decrease the potential of each region from $u_{i \alpha}$ to zero. No heat exchange with the bath occurs in this step and if the molecule is in region $\alpha$, then the work done on it is $W_{1}=-u_{i \alpha}$.
(2) Next, divide each region into smaller volumes by inserting secondary walls, so that region $\alpha$ (which had volume $R_{i \alpha} V$ ) is divided into $m$ smaller regions with volumes $V_{\beta \alpha}$ $=P(\beta \mid \alpha) R_{i \alpha} V$. There will be $n m$ such smaller regions at the end, some of which might have zero volume. This step does not require an expenditure of work. If molecule was in region $\alpha$, then the probability that it will appear in the region $\beta \alpha$ with volume $V_{\beta \alpha}$ is $P(\beta \mid \alpha)$.
(3) Next, slowly change the volume of each of these $n m$ regions such that the volume of region $\beta \alpha$ is changed from $V_{\beta \alpha}$ to

$$
\begin{equation*}
V_{\beta \alpha}^{\prime}=R_{f \beta} P(\beta \mid \alpha) e^{I_{\beta}-s_{\beta \alpha}} V \tag{32}
\end{equation*}
$$

The work done on the molecule if it is in region $\beta \alpha$ is

$$
\begin{align*}
W_{2} & =k_{B} T \ln \frac{V_{\beta \alpha}}{V_{\beta \alpha}^{\prime}}  \tag{33}\\
& =k_{B} T\left(\ln \frac{R_{i \alpha}}{R_{f \beta}}-I_{\beta}+s_{\beta \alpha}\right) . \tag{34}
\end{align*}
$$

Note that no problem arises if a particular volume $V_{\beta \alpha}$ is zero, since the probability that the molecule is there is zero.
(4) Now, for each $\beta$, connect the regions with indices $\beta 1$, $\beta 2, \ldots, \beta n$ into a single connected region with volume

$$
\begin{equation*}
V_{\beta}^{\prime}=\sum_{\alpha} V_{\beta \alpha}^{\prime}=R_{f \beta} V \tag{35}
\end{equation*}
$$

by removing some parts of the walls. This step also does not require an expenditure of work.
(5) Next, move the walls slowly in such a way that each region has still the same total volume, but at the end, the walls become arranged just like the final configuration. This step is needed for aesthetical reasons only. As long as the volumes of each region remain the same, there is no work done.
(6) Now, slowly compress each region $\beta$ from volume $V_{\beta}^{\prime}$ to $V_{\beta}^{\prime \prime}=e^{-I_{\beta} V_{\beta}^{\prime}}$ by a movable piston. If the molecule is in region $\beta$, the work done on it is

$$
\begin{equation*}
W_{3}=k_{B} T \ln \frac{V_{\beta}^{\prime}}{V_{\beta}^{\prime \prime}}=k_{B} T I_{\beta} \tag{36}
\end{equation*}
$$

(7) Now, open a hole on the pistons used in step 6 (or remove them suddenly), and let the molecule freely expand from volume $V_{\beta}^{\prime \prime}$ back to volume $V_{\beta}^{\prime}$. The work done on the molecule is zero again. The steps 6 and 7 are needed to increase the total entropy by the desired amount. Note that step 7 is possible only if all $I_{\beta}$ are non-negative.
(8) Increase the potential energy of each region from zero to $u_{f \beta}$. The work done if the molecule is in region $\beta$ is $W_{4}$ $=u_{f \beta}$.

At this point, the system is brought to the final configuration. If the molecule is initially in region $\alpha$, then it will appear in region $\beta$ with probability $P(\beta \mid \alpha)$. The total work done when this is the case is

$$
\begin{align*}
W(\beta \leftarrow \alpha) & =\sum_{j=1}^{4} W_{j}  \tag{37}\\
& =u_{f \beta}-u_{i \alpha}+k_{B} T\left(\ln \frac{R_{i \alpha}}{R_{f \beta}}+s_{\beta \alpha}\right)  \tag{38}\\
& =F_{f \beta}-F_{i \alpha}+k_{B} T s_{\beta \alpha} . \tag{39}
\end{align*}
$$

Therefore, the excess heat of that transition is $s_{\beta \alpha}$.
Note that when all expansion and compression steps are done infinitely slowly there will be no fluctuations in the
excess heats. This implies that the process map $\phi$ is not onto if some inefficiencies are nonzero. It is obvious that the step 6 is responsible for this effect as it caused the evacuation of some part of the total phase space.

There is a stronger form of this theorem concerned with the general case where the system interacts with different heat baths at different temperatures. It states that inequalities (1) capture also all restrictions that are satisfied by individual heats dumped to the baths. In other words, if each $Q_{j}(\beta \leftarrow \alpha)$ are chosen such that the quantity $s_{\beta \alpha}$ defined in Eq. (8) satisfies Eq. (1), then it is possible to construct a process where the average heats dumped into each bath in each possible transition are given by the chosen quantities. The proof of this statement is not complicated; one only needs to change the step 3 of the process described above in an appropriate way. For this reason, the construction of the process and the proof of this stronger statement are left to the reader.

## III. DISCUSSION

Since the inequalities in Eq. (1) express all restrictions that can be placed on the excess heats, they contain other powerful relations. In this section, it will be shown that a number of relations that have been obtained by different researchers in different contexts can be derived from these inequalities. The simplicity of these derivations is an indication of the power of these inequalities. A few other implications of these relations are also discussed at the end.

## A. Penrose's lower bounds on excess heats

As each term in Eq. (1) has to be less than 1, the following lower bound for the excess heats in terms of the corresponding transition probabilities can be given:

$$
\begin{equation*}
s_{\beta \alpha} \geq \ln P(\beta \mid \alpha) \tag{40}
\end{equation*}
$$

Hence, some excess heats can be negative if the corresponding transition probabilities are less than one. This inequality has been first obtained by Penrose in his treatment of nondeterministic processes [4]. Inequalities in Eq. (1) enable us to see how the lower bound above can be accomplished. If, $\alpha$ is the only initial state that leads to the final state $\beta$, then this lower bound can be achieved. If possible initial states are more than one, then it is not possible to achieve the lower bound, but it is possible to approach arbitrarily close to it, at the expense of increasing $s_{\beta \lambda}$ for all $\lambda \neq \alpha$.

A bound on the fluctuations of the excess heats can also be obtained if they are Gaussian. In that case, the average of $\exp (-s)$ for an $\alpha$ to $\beta$ transition is

$$
\begin{equation*}
\left\langle e^{-s}\right\rangle_{\beta \alpha}=\exp \left(-s_{\beta \alpha}+\frac{1}{2} \Delta s_{\beta \alpha}^{2}\right), \tag{41}
\end{equation*}
$$

where $\Delta s_{\beta \alpha}$ is the standard deviation of the fluctuations. The upper bound on the standard deviation can then be obtained from Eq. (25) as

$$
\begin{equation*}
\Delta s_{\beta \alpha} \leq \sqrt{2\left[s_{\beta \alpha}-\ln P(\beta \mid \alpha)\right]} \tag{42}
\end{equation*}
$$

In other words, the fluctuations are necessarily suppressed if the lower bound in Eq. (40) is approached. However, if the
fluctuations are not Gaussian, it is not possible to find such bounds on the standard deviation.

## B. Landauer's erasure principle

Consider a Landauer erasure process where all initial states end up in the same final state, e.g., in state $\beta=1$ (i.e., a restore-to- 1 process). In this case, $P(\beta \mid \alpha)=\delta_{\beta 1}$, all inefficiencies except $I_{1}$ are infinite and for the final state 1 we have

$$
\begin{equation*}
e^{-I_{1}}=\sum_{\alpha} e^{-s_{1 \alpha}} \leq 1 . \tag{43}
\end{equation*}
$$

This relation has been first obtained by Szilard [11] in connection with his membrane model. Although Szilard associated changes in entropy with the measurement process, a correct interpretation would connect it to the erasure as discussed in Ref. [12].

In order to obtain a lower bound on average excess heats, it is convenient to introduce the Legendre transform of the information-theoretic entropy function, $\sigma(\mathbf{p})=-\Sigma_{\alpha} p_{\alpha} \ln p_{\alpha}$, of a probability distribution $\mathbf{p}=\left(p_{1}, p_{2}, \ldots, p_{n}\right)$. Let $\mathbf{x}$ $=\left(x_{1}, x_{2}, \ldots, x_{n}\right)$ be an $n$-tuplet of real numbers. The Legendre transform of $\sigma$ is

$$
\begin{align*}
J(\mathbf{x})= & \min _{\mathbf{p}}\left(\sum_{\alpha} p_{\alpha} x_{\alpha}-\sigma(\mathbf{p})\right)  \tag{44}\\
& =-\ln \left(\sum_{\alpha} e^{-x_{\alpha}}\right) \tag{45}
\end{align*}
$$

where the minimum is taken over all possible probability distributions. The definition above implies that the inequality

$$
\begin{equation*}
\sum_{\alpha} p_{\alpha} x_{\alpha}-\sigma(\mathbf{p}) \geq J(\mathbf{x}) \tag{46}
\end{equation*}
$$

is satisfied for all $\mathbf{p}$ and $\mathbf{x}$. Moreover, the inequality becomes an equality if and only if $p_{\alpha}=\exp \left[J(\mathbf{x})-x_{\alpha}\right]$.

Taking $x_{\alpha}=s_{1 \alpha}$ in Eq. (46) gives $J(\mathbf{x})=I_{1} \geq 0$ and

$$
\begin{equation*}
\sum_{\alpha} p_{\alpha} s_{1 \alpha} \geq \sigma(\mathbf{p}) \tag{47}
\end{equation*}
$$

If the system is a memory device and information is coded such that the state $\alpha$ appears with probability $p_{\alpha}$, then $\sigma(\mathbf{p})$ is the measure of information in nats stored by the device. If the same resetting process is applied on the device (or on an ensemble of such devices) irrespective of the state, then the left-hand side of Eq. (47) is the (ensemble) average of the excess heats. Therefore, this inequality states LEP. Note that the inequality holds for any probability distribution $\mathbf{p}$. As a result, it can be considered as an infinite set of mathematical relations between $s_{1 \alpha}$. Interpreted in this way, Eq. (47) is equivalent to Eq. (43).

## C. Generalized Landauer principle

The derivation above can be repeated for an arbitrary process as well, which leads to the generalized form of Landauer's principle. Consider a process with transition probabilities $P(\beta \mid \alpha)$ and excess heats $s_{\beta \alpha}$. If the system is prepared in
the initial configuration with probability distribution of states being $p_{\alpha}$, then

$$
\begin{equation*}
\widetilde{p}_{\beta}=\sum_{\alpha} P(\beta \mid \alpha) p_{\alpha} \tag{48}
\end{equation*}
$$

is the probability distribution of final states and

$$
\begin{equation*}
\bar{s}=\sum_{\alpha \beta} s_{\beta \alpha} P(\beta \mid \alpha) p_{\alpha} \tag{49}
\end{equation*}
$$

is the average excess heat. A lower bound on $\bar{s}$ can be obtained as follows.

First, consider a single final state $\beta$. If we take $x_{\alpha}=\left[s_{\beta \alpha}\right.$ $-\ln P(\beta \mid \alpha)]$ (for $\alpha=1,2, \ldots, n)$, then it can be seen that $J(\mathbf{x})$ is equal to the inefficiency $I_{\beta}$. Using inequality (46), we can then write

$$
\begin{equation*}
\sum_{\alpha}\left[s_{\beta \alpha}-\ln P(\beta \mid \alpha)\right] q_{\alpha}^{\prime}-\sigma\left(\mathbf{q}^{\prime}\right) \geq J(\mathbf{x})=I_{\beta} \tag{50}
\end{equation*}
$$

which is valid for all probability distributions $\mathbf{q}^{\prime}$. Using the particular distribution $q_{\alpha}^{\prime}=P(\beta \mid \alpha) p_{\alpha} / \widetilde{p}_{\beta}$ in this inequality gives

$$
\begin{equation*}
\sum_{\alpha}\left[s_{\beta \alpha} P(\beta \mid \alpha) p_{\alpha}+P(\beta \mid \alpha) p_{\alpha} \ln p_{\alpha}\right]-\widetilde{p}_{\beta} \ln \widetilde{p}_{\beta} \geq \widetilde{p}_{\beta} I_{\beta} \tag{51}
\end{equation*}
$$

Finally, summing over the final states $\beta$ gives

$$
\begin{equation*}
\bar{s}+\sigma(\widetilde{\mathbf{p}})-\sigma(\mathbf{p}) \geq \sum_{\beta} \widetilde{p}_{\beta} I_{\beta} . \tag{52}
\end{equation*}
$$

As each inefficiency has to be non-negative, we get the desired result,

$$
\begin{equation*}
\bar{s} \geq \sigma(\mathbf{p})-\sigma(\widetilde{\mathbf{p}}) \tag{53}
\end{equation*}
$$

This is identical in content with the nondecreasing property of Penrose's statistical entropy [4]. It is termed as the generalized Landauer principle by Maroney [9,10] as it relates the average excess heat emitted to the environment to the change in the information-theoretic entropy of logical-state distributions.

As the properties of the process [namely $P(\beta \mid \alpha)$ and $s_{\beta \alpha}$ ] are independent of the choice of the distribution $\mathbf{p}$, it is possible to view Eq. (53) as an infinite set of inequalities, one for each possible distribution $\mathbf{p}$, placed on the process. Although they have clear physical interpretations, these inequalities are weaker than and not equivalent to the main inequalities of this paper given in Eq. (1). The reason is that, all expressions in Eq. (53) is essentially a combination of $\bar{s}_{\alpha}=\Sigma_{\beta} P(\beta \mid \alpha) s_{\beta \alpha}$, the final-state average of the excess heat when the initial state is $\alpha$. For this reason, Eq. (53) places restrictions only on the averages $\bar{s}_{\alpha}$ and not on the individual excess heats associated with every transition.

Moreover, Eqs. (1) and (53) imply an opposite dependence between individual excess heats of transitions. As an example, consider a process where all inefficiencies are 0 , and one of the excess heats, say $s_{\beta \alpha}$, is desired to be decreased. Relation (53) alone implies that, this can be achieved by increasing another excess heat with the same initial state (e.g., $s_{\mu \alpha}$ with $\mu \neq \beta$ ) in such a way that $\bar{s}_{\alpha}$
remains the same. However, according to Eq. (1), this is not possible; $s_{\beta \alpha}$ can be decreased only by increasing another excess heat with the same final state (e.g., $s_{\beta \lambda}$ with $\lambda \neq \alpha$ ). For this reason, relations (53) are not sufficient for this kind of process engineering problems.

## D. Controlled processes

A trivial application of the inequalities in Eq. (1) is to controlled processes. Here, the process to be applied on a system $S$ is determined based on the logical state of another system $C$, the controller; but the controller does not change its logical state during the process. The controlled-NOT gate is a well-known example. The restrictions on the heat exchanges with the environment for such processes can be analyzed simply by imposing these restrictions for each individual process on $S$. To be precise, suppose that when the state of the controller is $k$, the process $A^{(k)}$ is applied on $S$ which has transition probabilities $P^{(k)}(\beta \mid \alpha)$ and excess heats $s_{\beta \alpha}^{(k)}$. For this case, the controlled process applied on the combined system $S+C$ has the following transition probabilities and excess heats:

$$
\begin{gather*}
P(\beta j \mid \alpha k)=\delta_{j k} P^{(k)}(\beta \mid \alpha)  \tag{54}\\
s_{\beta k, \alpha k}=s_{\beta \alpha}^{(k)} \tag{55}
\end{gather*}
$$

The inequalities (1) for the controlled process then are

$$
\begin{equation*}
\sum_{\alpha} P^{(k)}(\beta \mid \alpha) e^{-s_{\beta \alpha}^{(k)}} \leq 1 \tag{56}
\end{equation*}
$$

which must hold for all $\beta$ and $k$. Therefore, the controlled process satisfies inequalities (1) if and only if every individual process $A^{(k)}$ applied on $S$ satisfies the same inequalities.

An immediate application of the result above is to the measurement processes. In this case $C$ is the system whose state will be measured and $S$ plays the role of the recording instrument. Before the measurement, $S$ must be prepared in a standard state, say $\alpha=1$. The measurement is then a controlled process as above, where the individual process $A^{(k)}$ changes the state of $S$ from $\alpha=1$ to $\beta=k$ with certainty. As this is the only necessary requirement, it is possible to construct $A^{(k)}$ as a deterministic and logically reversible process and choose $s_{k, 1}^{(k)}=0$. This controlled process changes the logical states of $S+C$ from $(1, k)$ into $(k, k)$, i.e., the state of $C$ has been copied into $S$, and no excess heat is transferred to the environment in doing this. This is a simple, but general demonstration of the principle first stated by Bennett [3], i.e., thermodynamically reversible measurements can be done provided that the recording instrument is initialized in a standard state.

## E. Some further bounds and processes with doubly stochastic transition probabilities

The inequalities in Eq. (1) give the relation between excess heats of the same final state, e.g., it gives a restriction between $s_{\beta 1}, \ldots, s_{\beta n}$. The following lower bound on the largest of these quantities can be easily deduced

$$
\begin{equation*}
\max _{\alpha} s_{\beta \alpha} \geq \ln \left(\sum_{\alpha} P(\beta \mid \alpha)\right) \tag{57}
\end{equation*}
$$

where the equality applies if and only if $s_{\beta 1}=\ldots=s_{\beta n}$. From here, it is possible to show that the largest excess heat of all transitions, $\max _{\alpha \beta} s_{\beta \alpha}$, is bounded from below by $\ln (n / m)$. In other words, at least one excess heat should exceed that bound. This result, together with a corresponding one for final-state averages of excess heats, is also contained in the following proposition.

Proposition. The following are equivalent:
(a) $s_{\beta \alpha} \leq \ln (n / m)$ for all $\beta$ and $\alpha$,
(b) $\bar{s}_{\alpha} \leq \ln (n / m)$ for all $\alpha$, where $\bar{s}_{\alpha}=\Sigma_{\beta} P(\beta \mid \alpha) s_{\beta \alpha}$ denotes the final-state average of the excess heat for the initial state $\alpha$,
(c) $s_{\beta \alpha}=\ln (n / m)$ for all $\beta$ and $\alpha$, all inefficiencies are $I_{\beta}$ $=0$ and the transition probabilities satisfy

$$
\begin{equation*}
\sum_{\alpha} P(\beta \mid \alpha)=\frac{n}{m} \tag{58}
\end{equation*}
$$

Proof. As the implications (c) $\Rightarrow(\mathrm{a}) \Rightarrow$ (b) are trivial, we only need to show (b) $\Rightarrow$ (c). Suppose that (b) holds. First, consider a fixed $\alpha$. Strict convexity of the exponential function leads to

$$
\begin{equation*}
\frac{m}{n} \leq e^{-\bar{s}_{\alpha}} \leq \sum_{\beta} P(\beta \mid \alpha) e^{-s_{\beta \alpha}} \tag{59}
\end{equation*}
$$

where the rightmost inequality is an equality if and only $s_{\beta \alpha}=\bar{s}_{\alpha}$ for all $\beta$. Next, sum these inequalities over the initial state $\alpha$ and apply Eq. (1) to get

$$
\begin{equation*}
m \leq \sum_{\alpha} e^{-\bar{s}_{\alpha}} \leq \sum_{\alpha \beta} P(\beta \mid \alpha) e^{-s_{\beta \alpha}} \leq \sum_{\beta} 1=m \tag{60}
\end{equation*}
$$

As the leftmost and rightmost sides of this chain are equal, all of the individual terms are equal to each other. Therefore, all inequalities that are used to obtain it must have been equalities as well. As a result, $s_{\beta \alpha}=\bar{s}_{\alpha}=\ln (n / m)$ for all $\alpha$ and $\beta, I_{\beta}=0$ for all $\beta$ and Eq. (58) follows from these.

At this point, it is worth concentrating on a particular special case, the case where the initial and final configurations of the system are identical (and hence $n=m$ ). Most applications, for example memory elements used in computation, fall under the scope of this case. A minor result that follows from the proposition for this case is that for any process there should be a transition with a non-negative excess heat. Similarly, there should be a state $\alpha$ for which $\bar{s}_{\alpha}$ $\geq 0$.

The processes that satisfy the conditions of the proposition have some remarkable properties that should be mentioned. These are processes that have doubly stochastic transition probabilities

$$
\begin{equation*}
\sum_{\alpha} P(\beta \mid \alpha)=\sum_{\alpha} P(\alpha \mid \beta)=1 . \tag{61}
\end{equation*}
$$

In this case, it is possible to construct the process in such a way that all excess heats are zero which necessarily implies that the process is also efficient for all final states. The proposition is stating that any process that has nonpositive
excess heats for all transitions should be such a process.
The excess heats of these processes have absolutely no fluctuations. There are no macroscopic fluctuations because all excess heats are uniform, $s_{\beta \alpha}=0$, and there are no microscopic fluctuations because the process is efficient. If the logical states of the system are also symmetric, i.e., they have equal equilibrium energy and entropy, then absolutely no heat exchange occurs with the bath and there is no work done irrespective of the initial and final state. A contact with a bath is not even necessary to implement the process.

Moreover, successive application of two such processes yields a process that has the same feature. For this reason, they might find application in the implementation of probabilistic Turing machines. If the individual computation steps of such a machine have doubly stochastic transition probabilities, then it is possible to run the whole computation without any heat exchange with the environment and without any work done (assuming that the states are symmetric).

Furthermore, any probabilistic Turing machine can be adapted to have doubly stochastic transitions. Consider, for example, a step of the computation where a set of memory elements $S$ with $n$ logical states undergoes a logical operation with transition probabilities $P(\beta \mid \alpha)$, which may not be doubly stochastic. Let $A$ be an ancillary device having $n$ logical states, which is initially in state $i=1$. Consider an operation on $S+A$ which has the following transition probabilities:

$$
P^{\prime}(\beta j \mid \alpha i)= \begin{cases}\frac{1}{n} P(\beta \mid \alpha) & \text { if } i=1  \tag{62}\\ \frac{\left(n-r_{\beta}\right)}{n^{2}(n-1)} & \text { if } i \neq 1\end{cases}
$$

where $r_{\beta}=\Sigma_{\alpha} P(\beta \mid \alpha)$ and the roman letters denote the logical states of $A$. It can be seen that $P^{\prime}$ is doubly stochastic and $\sum_{j} P^{\prime}(\beta j \mid \alpha 1)=P(\beta \mid \alpha)$. In other words, if $A$ starts in state 1 , then same logical operation is obtained on $S$. In order to make the whole computation doubly stochastic, different ancillaries with the same initial state have to be used at each computation step. This discussion essentially shows that probabilistic Turing machines with doubly stochastic transition probabilities can have the same computing power as any other probabilistic machine, at the expense of using a larger memory space.

However, it should be kept in mind that probabilistic Turing machines can also be designed to have deterministic computation steps where randomness is introduced by an additional input tape containing random symbols. They are more manageable for thermodynamically reversible computation since they can be adapted to have logically reversible computation steps as in Ref. [13]. In that case, they will also be able to erase all intermediate results of the computation, except the input, the desired output and the random tape, without any heat exchange. In addition, the symbols on the random tape can also be generated and subsequently erased without any heat exchange (e.g., inserting walls into a container containing single molecule for generation; removing the walls for erasing). As a result, there is no problem in doing probabilistic computation in a thermodynamically reversible way.

## IV. CONCLUSIONS

A complete set of inequalities has been obtained that places restrictions on the excess heats and the transition probabilities of any nondeterministic processes having feature (A). These inequalities can be interpreted as a generalized form of both Penrose's bound (40) for nondeterministic processes and Landauer's bound (43) for resetting operations. Their unique power comes from the completeness property. As a result, just like these two classical results, any relation between excess heats and transition probabilities can be obtained starting from these inequalities.

## APPENDIX: PROOF OF THEOREM 1 FOR VARYING TEMPERATURE CASE

Consider the general case where the process brings the system into contact with various heat baths at different temperatures. The notation is described in Sec. II A and the proof follows the same lines of the one given in Sec. II B. The quantum case is assumed because of its slightly better notation. It is also assumed that the baths $B_{i}$ and $B_{f}$ are distinct; the case where they are identical is not considered separately as the proof is altered only slightly. Suppose that there are $N$ baths and the initial and final baths are $B_{i}=B_{1}$ and $B_{f}=B_{N}$, respectively.

Let $n_{B_{j}}(E)$ denote the density of states of bath $B_{j}$ at energy $E$ which is defined by Eq. (26) and $N_{c \alpha}(E)$ denote the density of states of $S$ and $B_{c}$ for logical state $\alpha$ at configuration $c$ $=i, f$. These are defined as in Eq. (27) for the appropriate bath and can be expressed as $N_{c \alpha}(E)=n_{B_{c}}(E) Z_{c \alpha}\left(T_{c}\right)$.

Let $E_{1}, \ldots, E_{N}$ be a set of energies chosen in the appropriate temperature range of the corresponding baths and $E_{1}^{\prime}, \ldots, E_{N}^{\prime}$ be another set of energies. To simplify the notation, the shorthand $\mathcal{E}=\left(E_{1}, \ldots, E_{N}\right)$ and $\mathcal{E}^{\prime}=\left(E_{1}^{\prime}, \ldots, E_{N}^{\prime}\right)$ will be used. Consider the following set of microstates of the system and the baths:
(i) Initially, before the process is applied
(a) $S$ is in logical state $\alpha$,
(b) $S+B_{i}$ has energy in interval $\left(E_{1}, E_{1}+d E_{1}\right)$,
(c) bath $B_{j}(j \neq 1)$ has energy in interval $\left(E_{j}, E_{j}+d E_{j}\right)$;
(ii) and after the process is completed
(a) $S$ is in logical state $\beta$,
(b) $S+B_{f}$ has energy in interval $\left(E_{N}^{\prime}, E_{N}^{\prime}+d E_{N}^{\prime}\right)$,
(c) bath $B_{j}(j \neq N)$ has energy in interval $\left(E_{j}^{\prime}, E_{j}^{\prime}+d E_{j}^{\prime}\right)$.

The corresponding "density of states" for such microstates is given by

$$
\begin{align*}
M_{\beta \alpha}\left(\mathcal{E}^{\prime} ; \mathcal{E}\right)= & \operatorname{tr}\left(V \left[\theta_{i \alpha} \delta\left(E_{1}-H_{i S}-H_{B_{i}}\right)\right.\right. \\
& \left.\times \prod_{j \neq i} \delta\left(E_{j}-H_{B_{j}}\right)\right] V^{\dagger}\left[\theta_{f \beta} \delta\left(E_{N}^{\prime}-H_{f S}-H_{B_{f}}\right)\right. \\
& \left.\left.\times \prod_{j \neq f} \delta\left(E_{j}^{\prime}-H_{B_{j}}\right)\right]\right), \tag{A1}
\end{align*}
$$

where $V$ is the isometry corresponding to the time development of the state from $t_{1}$ to $t_{2}$. It satisfies $V^{\dagger} V=1$ and $V V^{\dagger}$ $\leq 1$. Note that, $E_{1}$ and $E_{N}^{\prime}$ include also the energy of thesystem $S$, while all the other energies represent only the corresponding bath's energy.

The density of states in Eq. (A1) can be easily related to the process dependent probabilities. First, note that by equal a priori probabilities, all microstates satisfying condition (i) above can be represented by the density matrix

$$
\begin{equation*}
\rho=\frac{1}{\mathcal{Z}} \theta_{i \alpha} \delta\left(E_{1}-H_{i S}-H_{B_{i}}\right) \prod_{j \neq i} \delta\left(E_{j}-H_{B_{j}}\right), \tag{A2}
\end{equation*}
$$

where

$$
\begin{equation*}
\mathcal{Z}=\sum_{\beta} \int d \mathcal{E}^{\prime} M_{\beta \alpha}\left(\mathcal{E}^{\prime} ; \mathcal{E}\right)=Z_{i \alpha}\left(T_{1}\right) \prod_{j=1}^{N} n_{B_{j}}\left(E_{j}\right) \tag{A3}
\end{equation*}
$$

As a result, $\rho^{\prime}=V \rho V^{\dagger}$ is the density matrix when the process is completed. Projective measurements by $\left\{\theta_{f \beta}\right\}$ will result in the transition probabilities

$$
\begin{equation*}
P(\beta \mid \alpha)=\operatorname{tr} \rho^{\prime} \theta_{f \beta}=\frac{1}{\mathcal{Z}} \int d \mathcal{E}^{\prime} M_{\beta \alpha}\left(\mathcal{E}^{\prime} ; \mathcal{E}\right) \tag{A4}
\end{equation*}
$$

Finally, if collapse to $\beta$ state occurs in that measurement, the final density matrix is $\rho^{\prime \prime}=\theta_{f \beta} \rho^{\prime} \theta_{f \beta} / P(\beta \mid \alpha)$ from which the distribution of final energies of the baths and the system, i.e., the function $\mathcal{P}_{\beta \alpha}\left(\mathcal{E}^{\prime}-\mathcal{E}\right)$ can be computed. The quantity defined in Eq. (A1) contains this information. As such, it can be expressed as

$$
\begin{equation*}
M_{\beta \alpha}\left(\mathcal{E}^{\prime} ; \mathcal{E}\right)=P(\beta \mid \alpha) \mathcal{P}_{\beta \alpha}\left(\mathcal{E}^{\prime}-\mathcal{E}\right) Z_{i \alpha}\left(T_{1}\right) \prod_{j=1}^{N} n_{B_{j}}\left(E_{j}\right) \tag{A5}
\end{equation*}
$$

where again it is assumed that these probabilities have a weak dependence on initial energies $\mathcal{E}$ and it is supposed that this dependence can be taken as an implicit dependence on the temperatures.

Now, sum and integration of $M$ over initial state and energies gives

$$
\begin{equation*}
\sum_{\alpha} \int d \mathcal{E} M_{\beta \alpha}\left(\mathcal{E}^{\prime} ; \mathcal{E}\right) \leq Z_{f \beta}\left(T_{N}\right) \prod_{j=1}^{N} n_{B_{j}}\left(E_{j}^{\prime}\right) \tag{A6}
\end{equation*}
$$

where the inequality is introduced taking by into account that $V V^{\dagger} \leq 1$. Using Eq. (A5), the last inequality can be written as

$$
\begin{align*}
& \sum_{\alpha} P(\beta \mid \alpha) \int d \mathcal{E} \mathcal{P}_{\beta \alpha}\left(\mathcal{E}^{\prime}-\mathcal{E}\right) \frac{Z_{i \alpha}\left(T_{1}\right)}{Z_{f \beta}\left(T_{N}\right)} \prod_{j} \frac{n_{B_{j}}\left(E_{j}\right)}{n_{B_{j}}\left(E_{j}^{\prime}\right)} \\
& \quad=\sum_{\alpha} P(\beta \mid \alpha)\left\langle e^{-s}\right\rangle_{\beta \alpha} \leq 1 \tag{A7}
\end{align*}
$$

where now the variable $s$ is given by

$$
\begin{equation*}
s=\frac{F_{f \beta}\left(T_{N}\right)}{k_{B} T_{N}}-\frac{F_{i \alpha}\left(T_{1}\right)}{k_{B} T_{1}}+\sum_{j=1}^{N} \frac{E_{j}^{\prime}-E_{j}}{k_{B} T_{j}} . \tag{A8}
\end{equation*}
$$

Since

$$
\begin{align*}
& \left\langle E_{1}^{\prime}-E_{1}\right\rangle_{\beta \alpha}=Q_{i}(\beta \leftarrow \alpha)-U_{i \alpha}  \tag{A9}\\
& \left\langle E_{N}^{\prime}-E_{N}\right\rangle_{\beta \alpha}=Q_{f}(\beta \leftarrow \alpha)+U_{f \beta} \tag{A10}
\end{align*}
$$

$$
\begin{equation*}
\left\langle E_{j}^{\prime}-E_{j}\right\rangle_{\beta \alpha}=Q_{j}(\beta \leftarrow \alpha) \quad(j \neq 1, N), \tag{A11}
\end{equation*}
$$

it can be seen that $\langle s\rangle_{\beta \alpha}=s_{\beta \alpha}$. The inequalities in Eq. (1) then follow by using the convexity of the exponential function. The detailed relation in Eq. (25) between the probability distributions for reversed and forward processes continues to hold in this case as well.
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